

Amendments to the Claims:

This listing of claims will replace all prior versions and listings of claims in the application:

Listing of Claims:

1. (Currently Amended) A drive assist system for [[an]] a driver's own vehicle at least having a solid object detecting unit for detecting frontal solid objects including a first preceding vehicle traveling ahead of said own vehicle and a second preceding vehicle traveling ahead of said first preceding vehicle and a traveling control unit including a constant speed traveling control unit for controlling a vehicle speed of said own vehicle so as to travel at a constant speed and follow-up traveling control unit for establishing said preceding vehicle as a follow-up object and for controlling [[a]] traveling of said own vehicle so as to follow [[up]] said preceding vehicle, comprising:

means for inhibiting an acceleration of said own vehicle following [[up]] said first preceding vehicle according to said follow-up traveling control unit when a first state is detected where said first preceding vehicle undertakes to pass said second preceding vehicle ~~is detected~~;

means for continuing to establish said first preceding vehicle as said follow-up object until a second state is detected where said first preceding vehicle travels in parallel with said second preceding vehicle ~~is detected~~;

means for changing said follow-up object from said first preceding vehicle to said second preceding vehicle when said second state changes to a third state where the speed of said first preceding vehicle is larger than that of said second preceding vehicle; and

means for continuing to establish said first preceding vehicle as said follow-up object when said second state changes to a fourth state where the speed of said first preceding vehicle is smaller than that of said second preceding vehicle.

2. (Currently Amended) The drive assist system according to claim 1, wherein said solid object detecting unit includes means for calculating at least ~~either~~ one of widths of said first preceding vehicle and said second preceding vehicle and means for discriminatingly recognizing said first preceding vehicle and said second preceding vehicle based on the direction of the first preceding vehicle passing the second preceding vehicle and said widths.
3. (Currently Amended) The drive assist system according to claim 1, wherein said traveling control means includes ~~means~~ unit for raising an alarm when it is judged that said second preceding vehicle is a stationary object.
4. (Currently Amended) The drive assist system according to claim 1, wherein said first state is detected by such judgment that an intervehicle distance between said first preceding vehicle and said second preceding vehicle decreases.
5. (Currently Amended) The drive assist system according to claim 1, wherein said first state is detected by such judgment that said first preceding vehicle moves ~~widthwise~~ sideways and said second preceding vehicle is detected.
- [[5]]6. (Currently Amended) The drive assist system according to claim 1, wherein said second state is detected by such judgment that a distance to said first preceding vehicle and a distance to said second preceding vehicle is approximately equal.
- [[6]]7. (Currently Amended) The drive assist system according to claim 1, wherein said first preceding vehicle is a two-wheel vehicle.